

Oriental Motor FA Network Compatible Products

FA NETWORK

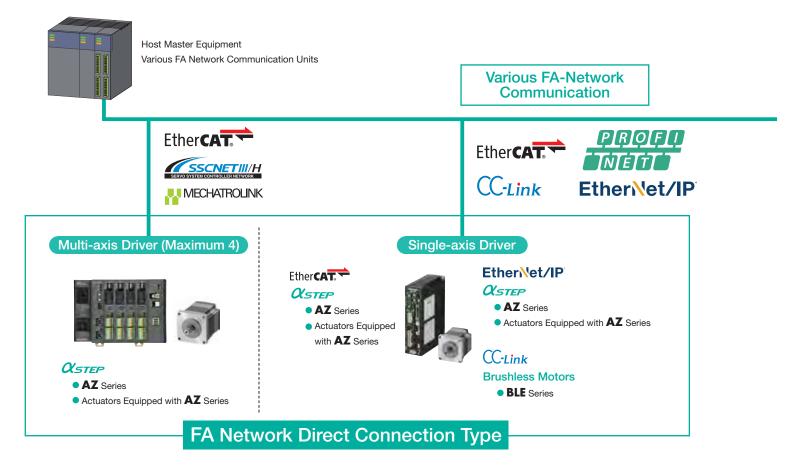
COMPATIBLE PRODUCTS



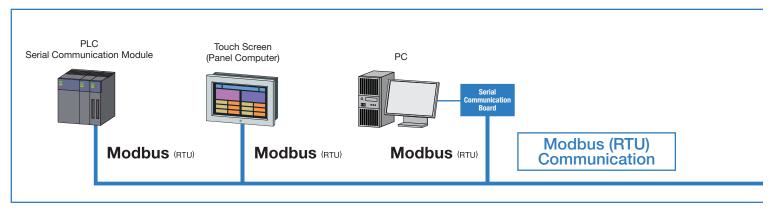
FA Network Compatible Products can Handle a Wide Variety of Equipment Design Requirements.

There are two main types of Oriental Motor FA Network-compatible products.
"FA Network direct connection type" and "Gateway connection type".
Highly versatile Modbus (RTU) communication is also supported.
→ P.6 Usage Examples for FA Network-Compatible Products

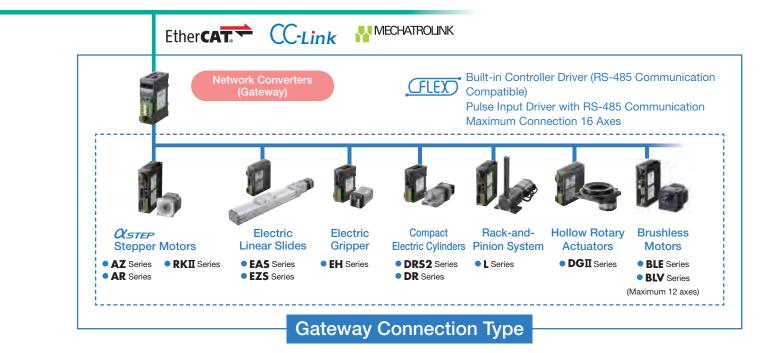
Product Line for FA Network-Compatible Products



Control from a variety of host devices is possible using Modbus (RTU)



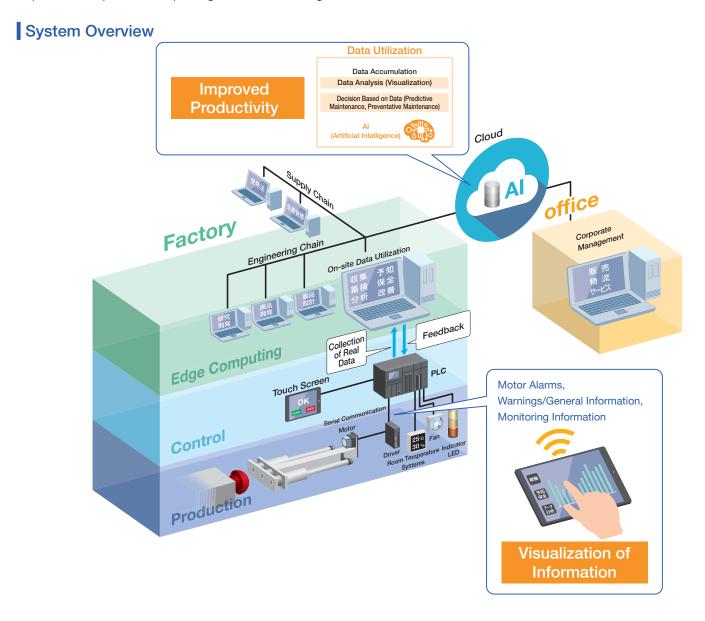






Contributes to Analysis of Conditions

Increased productivity is sought in manufacturing plants. At the same time, it is imperative to continue utilizing the knowledge of human experience through the use of Artificial Intelligence (AI). In order to use AI, it is important to collect, digitize and analyze the day to day "changes in conditions". Oriental Motor has created a wide lineup of products capable of outputting the various changes in conditions of motors.



Demonstrations of Predictive Maintenance and IoT can be Viewed on Our Website.

www.orientalmotor.com/videos/index.html

List of Alarms, Warnings/General Information and Monitors for Each Series

The monitoring functions, which contribute to analysis, are introduced below. For details, check the operating manual for each product.

Stepper Motors

Series Name Type		CVD Series	RKII Series	<i>ASTEP</i> AR Series	<i>OLSTEP</i> AZ Series
		RS-485 Communication	Built-in Positioning Function	Built-in Controller	Built-in Controller Pulse Input with RS-485 Communication EtherNet/IP Compatible EtherCAT Drive Profile Compatible
	Positioning	○ *1	O*2	0	0
	Speed	O*1	O*1	0	0
	Torque/Load	-	-	-	0
	Integrating Load	-	_	-	0
Monitoring	Motor Temperature	-	-	_	0
	Driver Temperature	0	-	-	0
	Distance Traveled Integrating Distance Traveled	0	_	_	0
	Overflow	-	○ *3	0	0
	Overspeed	-	-	0	0
	Overload	_	-	0	0
Warning/	Integrating Load	_	_	-	0
General	Motor Overheat	_	-	_	0
Information	Driver Overheat	0	0	0	0
	Distance Traveled Integrating Distance Traveled	0	_	_	0
	Overflow	-	○ *3	0	0
	Overspeed	—	_	0	0
Alarm	Overload	-	-	0	0
	Motor Overheat	—	_	-	0
	Driver Overheat	0	0	0	0

*1 Only the command values can be monitored.
 *2 For products with an encoder, the command value and the encoder counter value can be monitored.
 *3 Only for products with an encoder

Brushless Motors

Series Name Type		BLE Series	BLV Series	BLH Series
		RS-485 Communication		RS-485 Communication Type Digital Setting
	Torque/Load	_*1	○* ¹	O*1
Monitoring	Speed		○* ²	O*2
wontoning	Position Regulation	-	-	_
	Driver Temperature	-	-	* 3
	Motor Lock/Overload	0	0	0
Warning/	Overspeed	0	-	0
General	Overflow	_	_	-
Information	Driver Overheat	0	0	0
mormation	Distance Traveled Integrating Distance Traveled	_	_	0
	Motor Lock/Overload	0	0	0
	Overspeed	0	0	0
Alarm	Overflow	_	-	-
	Motor Overheat	-	_	-
	Driver Overheat	0	0	0

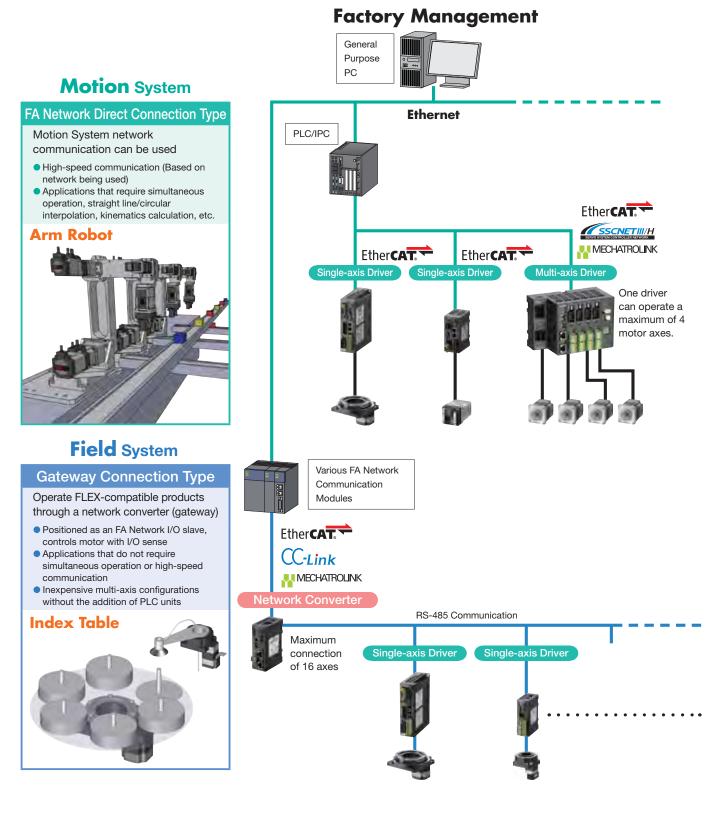
*1 Can be monitored using Support Software MEXEO2 or RS-485 communication.
 *2 Can be monitored using SPEED OUT output or Support Software MEXEO2.
 *3 Requires Support Software MEXEO2.

Usage Examples for FA Network-Compatible Products

Application cases for the FA Network Direct Connection Type and the Gateway Connection Type will be introduced below.

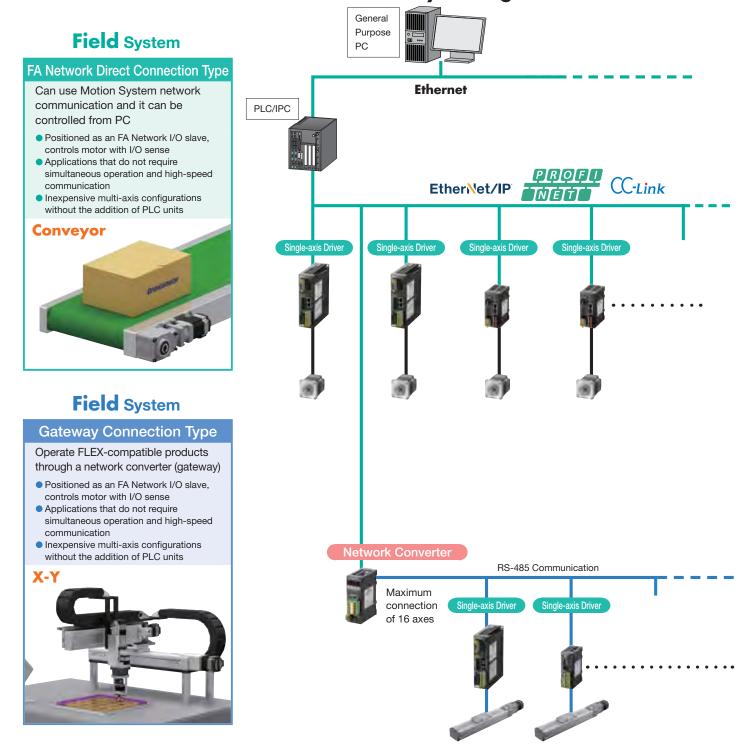
Capabilities of Network Products

- Setting of operating data from the network and overwriting of data at any time
- Implementation of the monitoring necessary for analysis



- What is a **Motion** System? Applications that require linear/circular interpolation, kinematics calculations or complicated calculation processing High-speed communication is necessary for simultaneous/synchronized operation of multiple motors.
- What is a **Field** System? Applications that do not require simultaneous/synchronized operation and can be positioned as an I/O slave within an FA Network High-speed communication is not necessary.

Factory Management



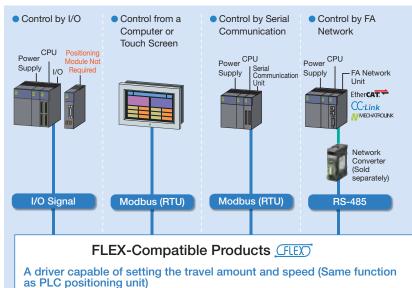
What is FLEX?

What is FLEX?

FLEX is the collective name for products that support I/O control, Modbus (RTU) control, and FA network control via network converters. These products enable simple connection and simple control, and shorten the total lead time for system construction. The <u>GEEX</u> logo in the series name indicates the applicable products.

Advantages

Because operation data is set and stored in the driver (positioning function is built-in), a PLC positioning module is not required, and system configuration is simple for multi-axis control.



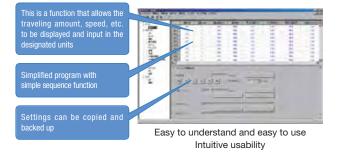
[Data Setting Method] ● Set from FA networks through a network converter ● Setting can be done by data setting software or RS-485 communication.

A Tool to Make All Data Setting Easy

• Support Software MEXE02 (Free Download)

Fundamental settings, such as editing operation data and parameter settings, can be performed easily from a computer.

Sequence control is possible, which allows for easy system configuration without a host sequence.









Easy to use, even for people with no electrical design

experience

Built-in waveform monitor that can check signal input status

Control Module OPX-2A (Sold Separately)

Startup data setting and operation checks can be performed, even without a computer. Suitable for on-site I/O check operation monitoring and setting changes.



• Touch Screen (Commercially Available)

Operating data can be directly overwritten from the touch screen normally used for monitoring. This is useful for monitoring operation status and when settings must be changed due to set-up changes.



System Configuration Examples

I/O Control

Operation data (travel amount, speed, etc.) is set in the driver in advance. When a signal is input from the directly connected PLC, operation is performed using the setting data. A positioning module and pulse generator are not necessary, thus saving space and simplifying the system.

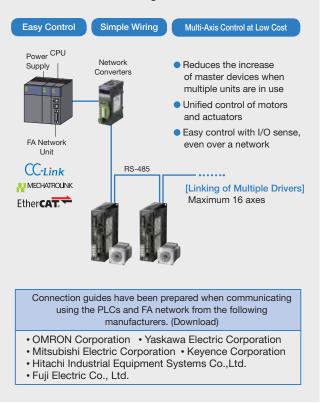
This kind of configuration is possible ►

Switch Box



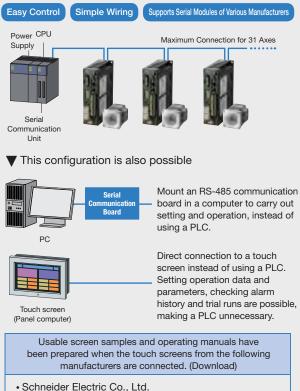
FA Network Control Via Network Converter

All FA network types are supported when a network converter is used. The setting of operating data and operation commands input is performed from the network. Multiple motors can be connected to and controlled by a single converter without the need to increase the number of host masters, contributing to a reduction in total costs.



Modbus (RTU) Control

RS-485 communication can be used to set operating data and parameters, as well as input operation commands. The protocol is Modbus (RTU) compatible, and can be easily controlled from a PLC or other device.



- Mitsubishi Electric Corporation
 Keyence Corporation
- Hakko Electronics Co., Ltd

FA Network Direct Connection-Compatible Products

Products that can be connected directly to an FA Network master device

Series Name	Features	Motor Types	FA Network
	 Automatic control that combines the tuning-free, high responsiveness of open loop control with the position correction and constant status monitoring function of closed loop control High performance Reduces return-to-home time and allows for motion control without the use of external sensors (Built-in battery-free absolute sensor) 	[Motor Size] 20 (0.79)/28 (1.10)/30 (1.18)/ 40 (1.57)/42 (1.65)/60 (2.36)/ 85 (3.35)/90 (3.54) [Geared Motor Types] TS/PS/HPG/Harmonic Geared Right-Angle FC Geared [Actuator Types] • Electric Linear Slides EAS Series • Electric Linear Slides EAS Series • Electric Cylinders EAC Series • Electric Cylinders EAC Series • Compact Electric Cylinders DRS2 Series • Compact Electric Cylinders DR Series • Hollow Rotary Actuators DGII Series • Rack-and-Pinion System L Series • Electric Gripper EH Series	Ether CAT.
Brushless Motors BLE Series CC-Link-Compatible AC Input Brushless Motors BLH Series RS-485 Communication Type	 Speed control and torque control are possible Speed control range: 80 to 4000 r/min Speed regulation with respect to the load: ±0.2% Wide product lineup for output power, gearheads and options 	[Motor Output Power] 30 W (1/25 HP)/60 W (1/12 HP)/ 120 W (1/6 HP) [Combination Type] • Parallel Shaft Gearhead • Hollow Shaft Flat Gearhead [Motor Output Power] 15 W (1/50 HP)/30 W (1/25 HP)/ 50 W (1/15 HP)	CC-Link (Ver.1.1)
DC Input	 A combination of the compact CVD Series stepper motor driver capable of high current operation with the compact, high torque PKP Series stepper motor High efficiency motor, decreased heat generation Full-time micro step operation with digital control 	[Combination Type] ● Parallel Shaft Gearhead ● Hollow Shaft Flat Gearhead [Motor Size] 2-Phase: □20 (0.79)/□28 (01.10)/ □35 (1.30)/□42 (1.65)/ □50 (1.97)/□51 (2.00)/ □56.4 (2.22)/□60 (2.36)/ □61 (2.40) 5-Phase: □20 (0.79) (PK Series)/ □28 (1.10)/□42 (1.65)/ □60 (2.36) [Geared Motor Types] 2-Phase: SH/CS Geared,	Modbus (RTU) Modbus (RTU)

Network Converter

Connects FLEX-Compatible Products to FA Networks

Network converters convert the various FA Network communication protocols to Oriental Motor's original RS-485 communication protocol.

Using a network converter makes it possible to control Oriental Motor FLEX-compatible products (RS-485 communicationcompatible) using all types of FA Network communication.

• Multi-Axis Connection is Possible

Product Name	Communication Protocol	Maximum Number of Connectable Units		Setting Me	thod for Converter	
NETCO2-CC	Ver. 2 Compatible	16	Body Control Panel		USB Cable Standard: USB2.0 (Full Speed) Type: A to mini B	_
NETCO1-CC	Ver. 1.1 Compatible	12	CC-Link Communication			
NETCO1-M2	(MECHATROLINK-II)		_	Support Software MEXE02 (Free download)	Support Software Communication Cable CC05IF-USB (Sold separately)	Control Module* OPX-2A (Sold separately)
NETCO1-M3	(MECHATROLINK (MECHATROLINK-III)	16	_			0
NETCO1-ECT	Ether CAT		EtherCAT Communication			

*The control module can also be used as a scan-time monitor during communication.

Gateway Connection Type FLEX-Compatible Products

AZ Series with Built-In Battery-Free Absolute-Sensor

Series Name	Features	Motor Types	FA Network
ØSTEP AZ Series AC Input DC Input	 Automatic control that combines the tuning- free, high responsiveness of open loop control with the position correction and constant status monitoring function of closed loop control Reduces return-to-home time and allows for motion control without the use of external sensors Number of positioning points: 256 points 	AC Input [Motor Size] □40 (1.57)/□42 (1.65)/□60 (2.36)/ □85 (3.35)/□90 (3.54) [Geared Motor Type] TS/PS/HPG/Harmonic Geared Type Right-Angled FC Geared ● DC Input [Motor Size] □20 (0.79)/□28 (1.10)/□30 (1.18)/ □40 (1.57)/□42 (1.65)/□60 (2.36) [Geared Motor Type] TS/PS/HPG/Harmonic Geared Type Right-Angle FC Geared	
Electric Linear Slides EZS Series AC Input DC Input	 Linear slide that combines the AZ Series with a ball screw and guide from THK. Simple dust proofing function, clean room compatible Slim dimensions Stroke: 50 to 850 mm Max. Speed: 800 mm/s Maximum Transportable Mass - Horizontal: 60 kg (132.3 lb) Maximum Transportable Mass - Vertical: 30 kg (66.1 lb) Thrust: 400 N 	 Straight Type EZS3, EZS4, EZS6 Reversed Type EZS3, EZS4, EZS6 Cleanroom compatible EZS3, EZS4, EZS6 	Connection to FA
Electric Cylinders EAC Series AC Input DC Input	Electric cylinder that combines the AZ Series with a ball screw and guide from THK. • Stroke: 50 to 300 mm • Max. speed: 600 mm/s • Maximum Transportable Mass - Horizontal: 60 kg (132.3 lb) • Maximum Transportable Mass - Vertical: 30 kg (66.1 lb) • Thrust: 400 N	 Straight Type EAC2, EAC4, EAC6 *EAC2 is DC input only Reversed Type EAC4, EAC6 	Network via Network Converter or Modbus (RTU)
Compact Electric Cylinders DR Series DC Input	Integration of an AZ Series motor with a ball screw saves space and reduces wiring. Optimized for providing linear motion micro-movements and high positioning accuracy applications. Push-motion operation is also possible. * • Minimum Traveling Amount: 0.001 mm • Repetitive Positioning Accuracy: ±0.003 mm • Maximum Transportable Mass - Horizontal: 4 kg (8.8 lb) • Maximum Transportable Mass - Vertical: 4 kg (8.8 lb) • Max. Speed: 100 mm/s * □28 mm lead 2.5 mm only	□28 mm	
Compact Electric Cylinders DR\$2 Series DC Input	Integration of an AZ Series motor with a ball screw saves space and reduces wiring. Optimized for providing linear motion micro-movements and high positioning accuracy applications. Push-motion operation is also possible. Minimum Traveling Amount: 0.001 mm Repetitive Positioning Accuracy: Ground ball screw: ±0.003 mm Rolled ball screw: ±0.01 mm Maximum Transportable Mass (Horizontal/ Vertical) 50 kg (110.2 lb) Max. Speed: 200 mm/s	□42 mm	

Series Name	Features	Motor Types	FA Network
Electric Gripper EH Series DC Input	This is an electric gripper that combines the AZ Series with a rack-and-pinion mechanism. A delicate "grasp" is possible at low-speed operation by adjusting the running current. • Max. Holding Force: 25 N • Repetitive Positioning Accuracy (One side): ±0.02 mm • Backlash (one side): 0.1 mm • Stroke: 25 mm • Minimum Traveling Amount: 0.02 mm • Max. Speed: 156 mm/s These are linear & rotary actuators that combine a rack-and-pinion mechanism with a linear motor. • High Transportable Mass/Long Stroke	EH4 • Horizontal (B Type) • Vertical (F Type)	Connection to FA
AC Input	 Stroke: 100 to 1000 mm Max. Speed: 500 mm/s Maximum Transportable Mass: 100 kg (220.5 lb) 		Network via Network Converter or Modbus (RTU)
Hollow Rotary Actuators DGII Series AC Input DC Input	 The AZ Series has been integrated with a large aperture hollow rotary table. Useful for Index Operations Attach Work Piece Directly to Table, Use Hollow Area for Piping Reduced Return-to-Home Time 	 Cross-Roller Bearing B5/_130/_200 mm *200 mm is AC input only Deep-Groove Ball Bearing 60 mm *DC power supply input only 	

Gateway Connection Type FLEX-Compatible Products

α_{STEP} **AR** Series

Series Name	Features	Motor Types	FA Network
QSTEP AR Series AC Input DC Input	 Automatic control that combines the tuning- free, high responsiveness of open loop control with the position correction and constant status monitoring function of closed loop control High Efficiency Motor IP65-rated Motor SEMI47-Compatible Number of Positioning points: 64 points 	AC Input [Motor Size] 42 (1.65)/_60 (2.36)/_85 (3.35)/ 90 (3.54) [Geared Motor Type] TH/PS/PN/Harmonic Geared Type Right-Angle Shaft FC Geared DC Input [Motor Size] 20 (0.79)/_28 (1.10)/_30 (1.18)/ 42 (1.65)/_60 (2.36)/_85 (3.35)/ 90 (3.54) [Geared Motor Type] TH/PS/PN/Harmonic Geared	
Electric Linear Slides EAS Series AC Input DC Input	 This is a standard type linear slide that combines the AR Series with a ball-screw and guide from THK. Stroke: 50 to 850 mm Max. Speed: 800 mm/s Maximum Transportable Mass - Horizontal: 60 kg (132.3 lb) Maximum Transportable Mass - Vertical: 30 kg (66.1 lb) Thrust: 400 N 	 Straight Type EAS2, EAS4, EAS6 *EAS2 is DC input only Reversed Type EAS4, EAS6 	Connection to FA Network via Network Converter or Modbus (BTU)
Electric Cylinders EAC Series AC Input DC Input	 This is an electric cylinder that combines the AR Series with a ball-screw and guide from THK. Stroke: 50 to 300 mm Max. Speed: 600 mm/s Maximum Transportable Mass - Horizontal: 60 kg (132.3 lb) Maximum Transportable Mass - Vertical: 30 kg (66.1 lb) Thrust: 400 N 	 Straight Type EAC2, EAC4, EAC6 *EAC2 is DC input only Reversed Type EAC4, EAC6 	
Hollow Rotary Actuators DGII Series AC Input DC Input	 The AR Series has been integrated with a large aperture hollow rotary table. Useful for Index Operations Attach Work Piece Directly to Table, Use Hollow Area for Piping 	 Cross-Roller Bearing 85/130/200 mm *AC Input only Deep-Groove Ball Bearing 60 mm *DC input only 	

Stepper Motor Open Loop Control

Series Name	Features	Motor Types	FA Network
Stepper Motors RKI Series AC Input	 This is a newly-designed 5-phase motor that utilizes a full-time microstepping driver with full digital control. High Efficiency Motor Low Vibration and Reduced Noise Compact AC Input Driver Misstep Detection via Encoder Number of Positioning Points: 64 points 	[Motor Size] 42 (1.65)/_60 (2.36)/_85 (3.35)/ 90 (3.54) [Geared Motor Type] TS/PS/Harmonic Geared Right-Angle Shaft FC Geared	Connection to FA Network via Network Converter or Modbus (RTU)

Brushless Motors

Series Name	Features	Motor Types	FA Network
Brushless Motors BLE Series RS-485 Communication Type		[Motor Output Power] 30 W (1/25 HP)/60 W (1/12 HP)/ 120 W (1/6 HP)	
AC Input	Parallel S	[Combination Type] Parallel Shaft Gearhead Hollow Shaft Flat Gearhead	
	 Speed Control, Torque Limiting Speed Control Range: 80 to 4000 r/min Speed Regulation with Respect to the Load: 		Connection to FA Network via Network Converter
Brushless Motors	±0.2%	[Motor Output Power]	or
BLV Series	 Wide Lineup of Output Power, Gearhead and Options 	100 W (1/18 HP)/200 W (1/4 HP)/ 400 W (1/2 HP)	Modbus (RTU)
		[Combination Type] Parallel Shaft Gearhead Hollow Shaft Flat Gearhead Round Shaft	



EtherCAT is an Ethernet (IEEE802.3)-compliant, open, high-speed, industrial network system.

•EtherCAT[®] is a registered trademark and patented technology, licensed by Beckhoff Automation GmbH, Germany.

CC-Link

CC-Link (Control&Communication Link) is the open field network promoted by CC-Link Partner Association.

•CC-Link is a registered trademark of CC-Link Partner Association.

MECHATROLINK

 $\label{eq:mechatrolink-II} \mbox{ and MECHATROLINK-III} are motion networks promoted by MECHATROLINK Members Association.$

•MECHATROLINK is a registered trademark of MECHATROLINK Members Association.



PROFINET is an Industrial Ethernet solution. It is a communication protocol to exchange data between controllers and devices.

•PROFINET is a trademark or registered trademark of PROFIBUS Nutzerorganisation e.V. (PNO).

EtherNet/IP

EtherNet/IP is the open field network promoted by ODVA (Open DeviceNet Vendor Association, Inc.) •EtherNet/IP is a trademark of ODVA.

Modbus (RTU)

Modbus is the open field network with Modbus Protocol installed. Modbus is used widely in the fields of factory and process automation because its protocol specification is open to the public and it is very simple.

•Modbus is a registered trademark of Schneider Automation Inc.



 $\ensuremath{\mathsf{SSCNET}}\xspace$ //H is the motion network promoted by Mitsubishi Electric Corporation.

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